

Statistical methods in cosmology

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**The
Alan Turing
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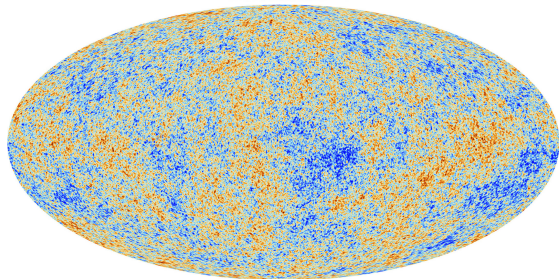
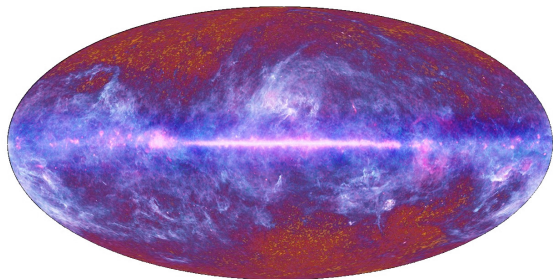


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CAMBRIDGE**



Lessons from the CMB

- ▶ 21cm global signal detection is superficially similar to detecting the primordial CMB.
- ▶ Both are attempted to detect tiny $\sim 10^{-5}$ cosmological signals hidden beneath a large “uninteresting” foreground.
- ▶ Both measurements are frustrated by complicated contaminants.
- ▶ Both are amenable to a Bayesian analysis.



The three pillars of Bayesian inference

- ▶ Parameter estimation: “What do the data tell me about my model?”:

$$P(\theta|D, M) = \frac{P(D|\theta, M)P(\theta|M)}{P(D|M)}, \quad \mathcal{P} = \frac{\mathcal{L} \times \pi}{\mathcal{Z}}, \quad \text{Posterior} = \frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}.$$

- ▶ Model comparison: “Which model best fits the data?”:

$$P(M|D) = \frac{P(D|M)P(M)}{P(D)}, \quad \frac{\mathcal{Z}_M \Pi_M}{\sum_m \mathcal{Z}_m \Pi_m}, \quad \text{Model Posterior} = \frac{\text{Evidence} \times \text{Model Prior}}{\text{Normalisation}}.$$

- ▶ Tension quantification: “Are datasets consistent within a given model?” [1902.04029]

$$\mathcal{R} = \frac{\mathcal{Z}_{AB}}{\mathcal{Z}_A \mathcal{Z}_B}, \quad \log \mathcal{S} = \langle \log \mathcal{L}_{AB} \rangle_{\mathcal{P}_{AB}} - \langle \log \mathcal{L}_B \rangle_{\mathcal{P}_A} - \langle \log \mathcal{L}_B \rangle_{\mathcal{P}_B}$$

What is a model?

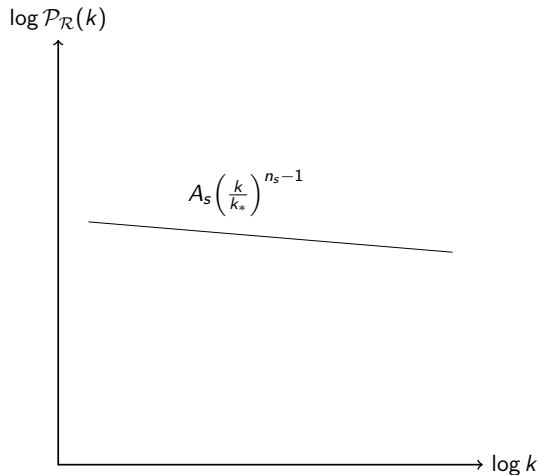
- ▶ Model comparison in its purest form answers question such as:
 - ▶ “Is the universe Λ CDM?”
 - ▶ “Are neutrinos in a normal or inverted hierarchy?”
 - ▶ “Is there a detectable global signal in this data?”
- ▶ However model \mathcal{M} is likelihood $\mathcal{L} = P(D|\theta, M)$ and priors $\pi = P(\theta|M)$, $\Pi = P(M)$
- ▶ Can use the evidence \mathcal{Z} to decide on which out of a set of likelihoods best describe data (e.g. Gaussian, Cauchy, Poisson, radiometric).
- ▶ Can also use it for antenna selection [2106.10193] [2109.10098].
- ▶ In principle can use it to decide between theoretically motivated priors (care needed)
- ▶ It can also be used for non-parametric reconstruction:
 - ▶ “How many polynomial terms best describe the data?”
 - ▶ “How complicated a sky model do I need?”
 - ▶ “Which is the best sky model?”

Primordial power spectrum $\mathcal{P}_{\mathcal{R}}(k)$ reconstruction [1908.00906]

- ▶ Traditionally parameterise the primordial power spectrum with (A_s, n_s)

$$\mathcal{P}_{\mathcal{R}}(k) = A_s \left(\frac{k}{k_*} \right)^{n_s-1}$$

- ▶ To add more degrees of freedom, can add “running” parameters n_{run} (higher order polynomial in index)
- ▶ Alternative non-parametric technique introduces a more flexible phenomenological parameterisation: “FlexKnots”
- ▶ Let the Bayesian evidence decide when you’ve introduced too many parameters

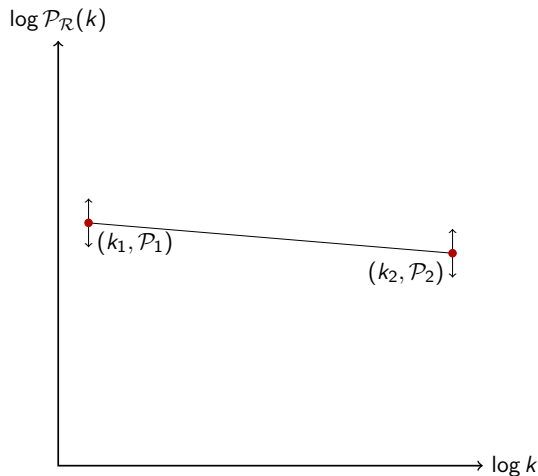


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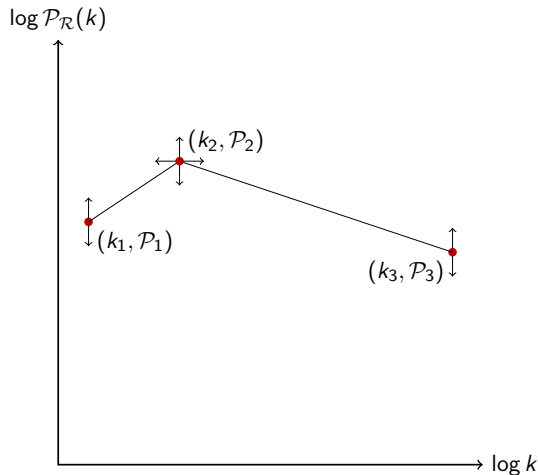


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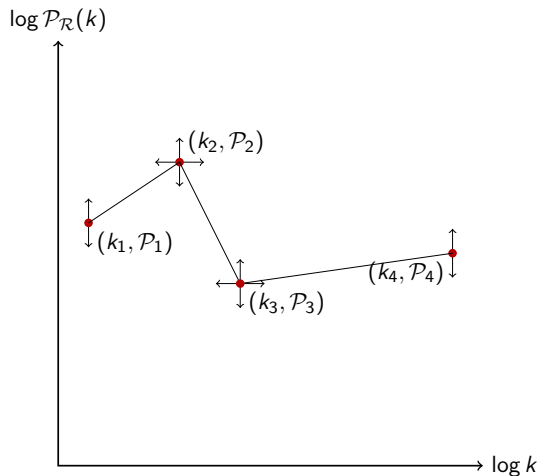


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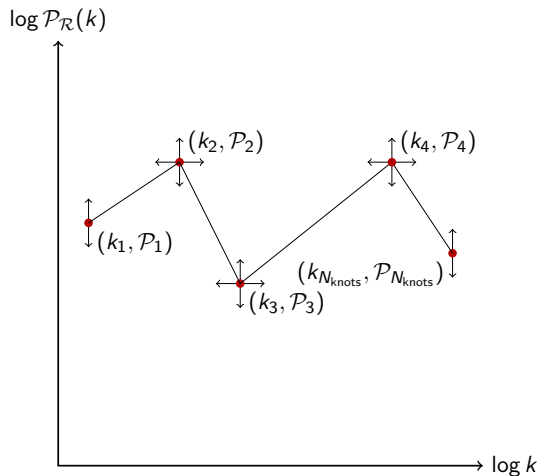


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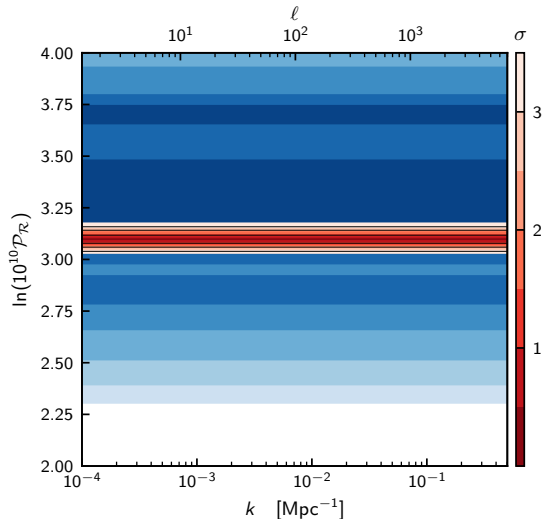


0 internal knots

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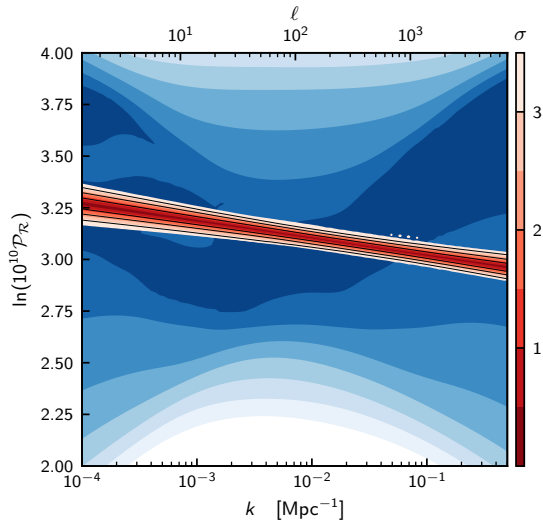


1 internal knot

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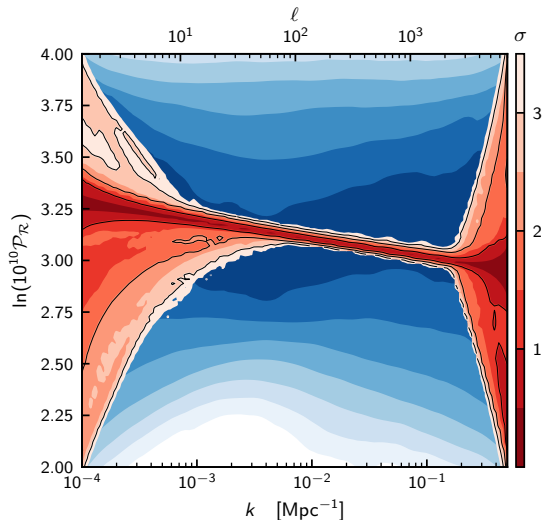


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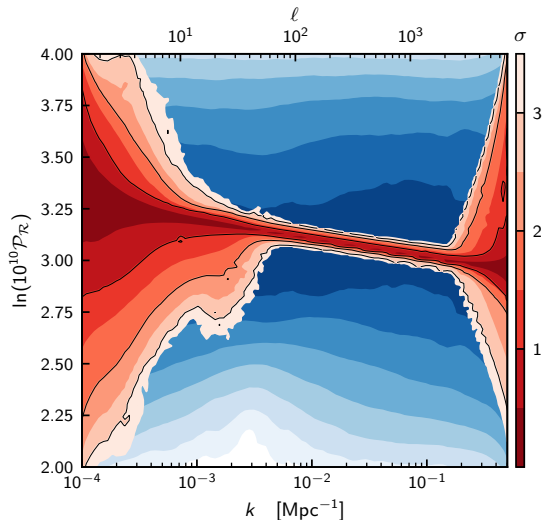


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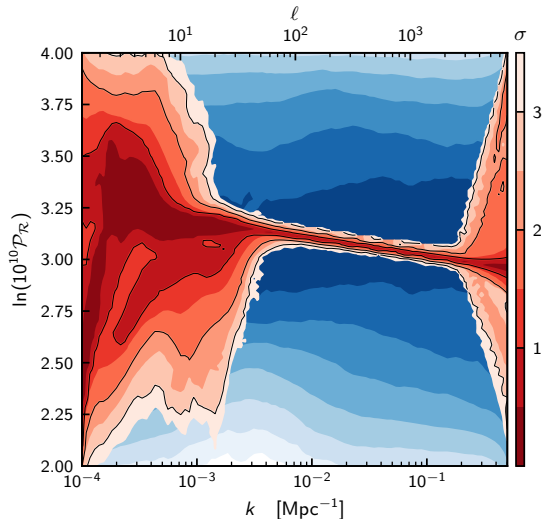


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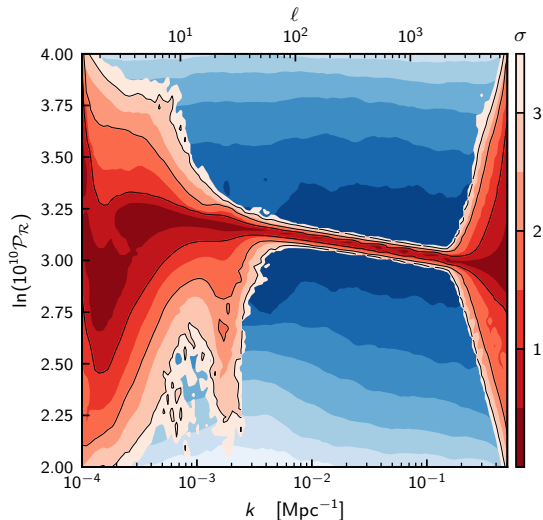


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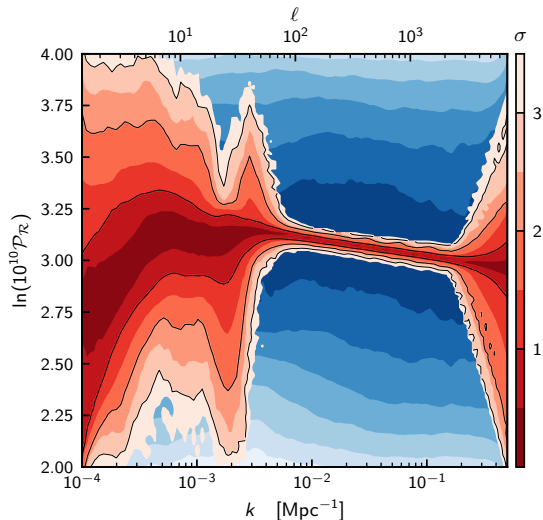


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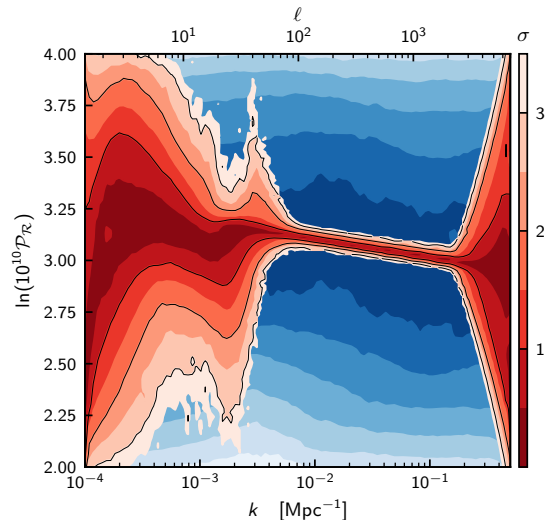
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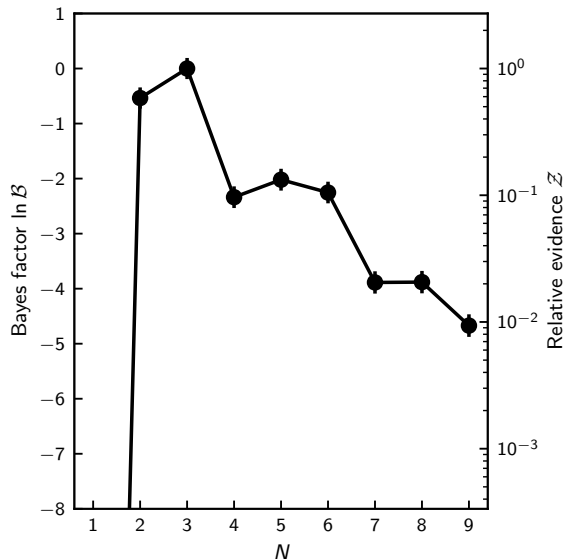


Bayes Factors

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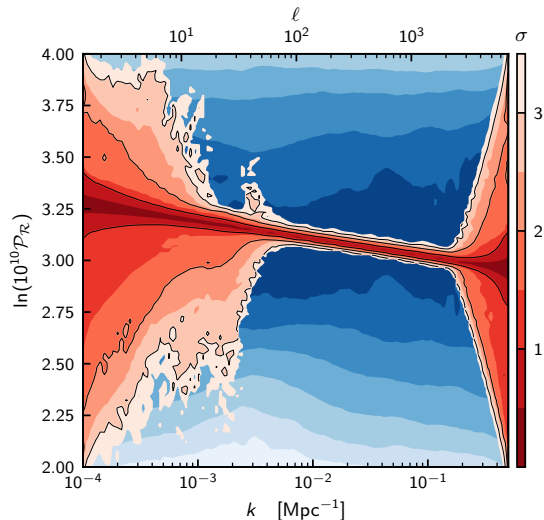
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Marginalised plot

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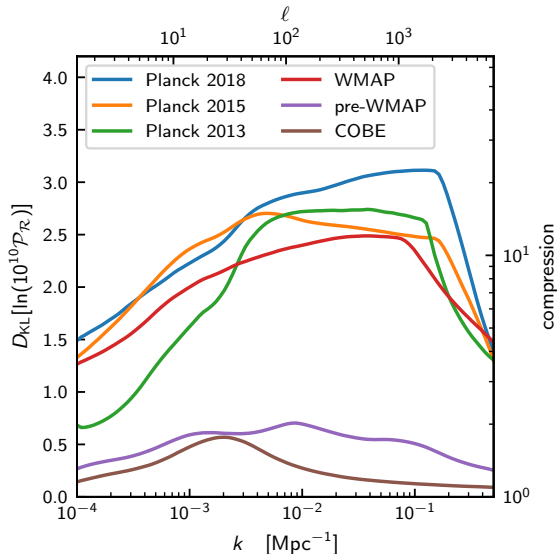


Kullback-Liebler divergences

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Occam's Razor [2102.11511]

- ▶ Bayesian inference quantifies Occam's Razor:
 - ▶ *"Entities are not to be multiplied without necessity"* — William of Occam
 - ▶ *"Everything should be kept as simple as possible, but not simpler"* — "Albert Einstein"
- ▶ Properties of the evidence: rearrange Bayes' theorem for parameter estimation

$$\mathcal{P}(\theta) = \frac{\mathcal{L}(\theta)\pi(\theta)}{\mathcal{Z}} \Rightarrow \log \mathcal{Z} = \log \mathcal{L}(\theta) - \log \frac{\mathcal{P}(\theta)}{\pi(\theta)}$$

- ▶ Evidence is composed of a "goodness of fit" term and "Occam Penalty"
- ▶ RHS true for all θ . Take max likelihood value θ_* :
- ▶ Be more Bayesian and take posterior average to get the "Occam's razor equation"

$$\log \mathcal{Z} = -\chi_{\min}^2 - \text{Mackay penalty}$$

$$\log \mathcal{Z} = \langle \log \mathcal{L} \rangle_{\mathcal{P}} - \mathcal{D}_{\text{KL}}$$

- ▶ Natural regularisation which penalises models with too many parameters.

Kullback Liebler divergence

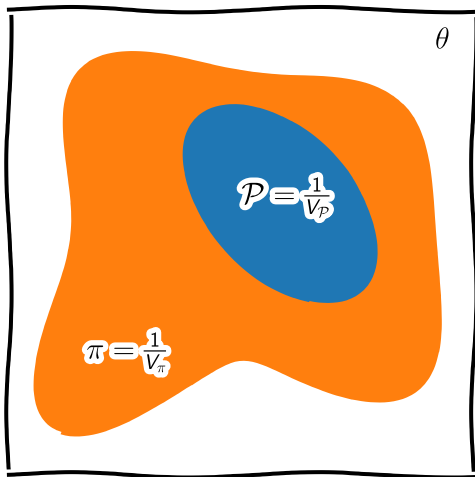
- ▶ The KL divergence between **prior** π and **posterior** \mathcal{P} is defined as:

$$\mathcal{D}_{\text{KL}} = \left\langle \log \frac{\mathcal{P}}{\pi} \right\rangle_{\mathcal{P}} = \int \mathcal{P}(\theta) \log \frac{\mathcal{P}(\theta)}{\pi(\theta)} d\theta.$$

- ▶ Whilst not a distance, $\mathcal{D} = 0$ when $\mathcal{P} = \pi$.
- ▶ Occurs in the context of machine learning as an objective function for training functions.
- ▶ In Bayesian inference it can be understood as a log-ratio of “volumes”:

$$\mathcal{D}_{\text{KL}} \approx \log \frac{V_{\pi}}{V_{\mathcal{P}}}.$$

(this is exact for top-hat distributions).

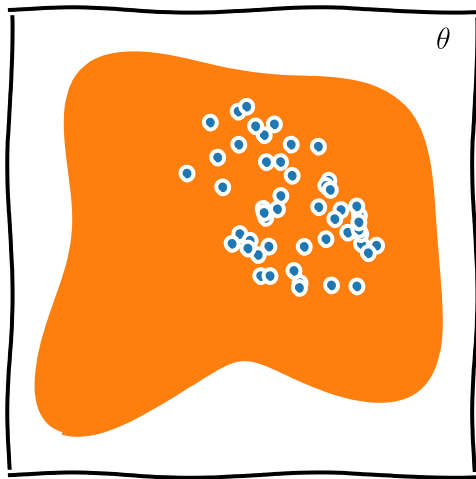


Why do sampling?

- ▶ The cornerstone of numerical Bayesian inference is working with **samples**.
- ▶ Generate a set of representative parameters drawn in proportion to the posterior $\theta \sim \mathcal{P}$.
- ▶ The magic of marginalisation \Rightarrow perform usual analysis on each sample in turn.
- ▶ The golden rule is **stay in samples** until the last moment before computing summary statistics/triangle plots because

$$f(\langle X \rangle) \neq \langle f(X) \rangle$$

- ▶ Generally need $\sim \mathcal{O}(12)$ independent samples to compute a value and error bar.



How to generate samples

- ▶ MCMC!
- ▶ chi-feng.github.io/mcmc-demo/

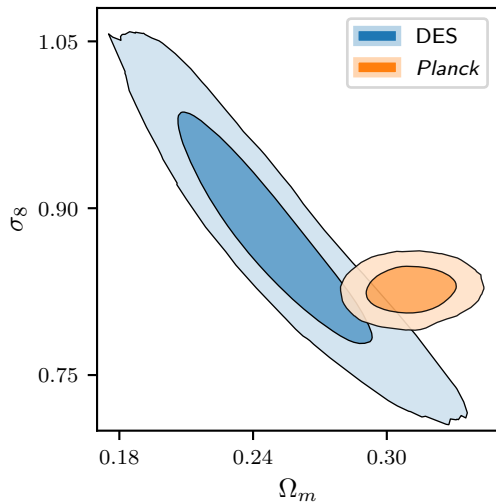
Nested Sampling: Benefits and drawbacks

Relative to traditional numerical posterior samples (Metropolis Hastings, HMC, emcee), nested sampling:

- + Can calculate evidence (and therefore perform model comparison).
- + Can calculate KL divergence.
- + Can handle multi-modal distributions.
- + Requires little tuning for an a-priori unseen problem.
- + Highly parallelisable ($n_{\text{cores}} \sim n_{\text{live}} \gg 4$).
- + Does not require gradients
- Slower than a well-tuned posterior sampler.
- Run time is dependent on prior choice, and priors must be proper (some people view this as a feature rather than a bug).

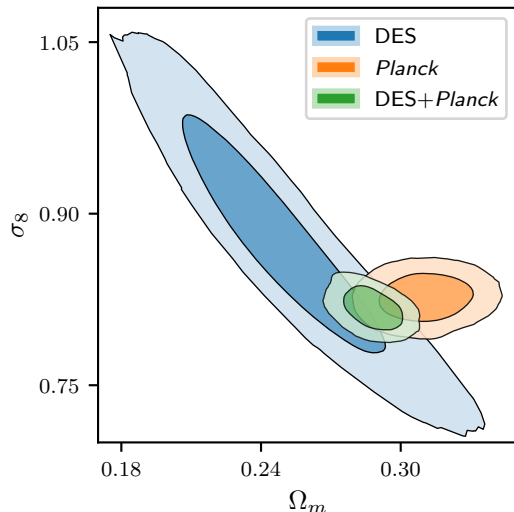
The importance of global measures of tension

- ▶ Hubble tension [1907.10625]
 - ▶ *Planck*: $H_0 = 67.4 \pm 0.5$
 - ▶ SH_0ES : $H_0 = 74.0 \pm 1.4$
- ▶ In other situations the discrepancy doesn't exist in a single interpretable parameter
- ▶ For example: DES+*Planck* [1902.04029]
- ▶ Are these two datasets in tension?
- ▶ There are a lot more parameters – are we sure that tensions aren't hiding? Are we sure we've chosen the best ones to reveal the tension?
- ▶ Should use “Suspiciousness” statistic \mathcal{S} , or Bayes ratio \mathcal{R} to determine global tension.



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Future extensions for REACH

- ▶ Tension quantification for cross validation
 - ▶ Between experiments
 - ▶ Between REACH antennae
 - ▶ Between different subsets of the REACH timestream
- ▶ Model marginalisation rather than comparison
- ▶ FlexKnot reconstructions
- ▶ Likelihood selection
- ▶ Occam factors on evidence plots.
- ▶ Integration of calibration and cosmology pipelines

- ▶ What was that awesome website?

Full credit to Chi-feng for this incredible online demonstration tool
chi-feng.github.io/mcmc-demo/

- ▶ How do you make your plots look hand-drawn?

```
import matplotlib.pyplot as plt  
plt.xkcd()
```